

4.2 ODE review

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Def. 4.1 A differential equation of order n is an equation
$$f\left(x, \frac{dx}{dt}, \frac{d^2x}{dt^2}, \dots, \frac{d^nx}{dt^n}, t\right) = 0$$
, where x is a function of t
$$f(x, \dot{x}, \ddot{x}, \dots, x^{(n)}, t)$$

Def. If an ODE does not depend explicitly on t , i.e.

$$f(x, \dot{x}, \dots, x^{(n)}, t) \equiv f(x, \dot{x}, \dots, x^{(n)}),$$

then it is **autonomous**. Otherwise, **nonautonomous**.

Def. An ODE that can be rewritten as

$$\frac{d^nx}{dt^n} + a_1(t) \frac{d^{n-1}x}{dt^{n-1}} + \dots + a_{n-1}(t) \frac{dx}{dt} + a_n(t) x = g(t).$$

is **linear**. Otherwise, **nonlinear**.

Def. If given a linear ODE of the form above, $g(t) \equiv 0$, then it is **homogeneous**. Otherwise, **nonhomogeneous**.

Def. A first-order system can be written as

$$\frac{dX}{dt} = F(X(t), t)$$

where

$$X(t) = \begin{bmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{bmatrix}, \quad F = \begin{bmatrix} f_1 \\ \vdots \\ f_n \end{bmatrix}, \quad f_i \equiv f_i(x_1(t), x_2(t), \dots, x_n(t), t)$$

Def. A first-order system is **autonomous** if $F(X(t), t) \equiv F(X(t))$, i.e. does not depend explicitly on t . **Nonautonomous** otherwise.

Def. A first-order system is **linear** if

$$\frac{dX}{dt}(t) = A(t)X(t) + G(t)$$

where

$$A(t) = \begin{bmatrix} a_{11}(t) & \dots & a_{1n}(t) \\ \vdots & \ddots & \vdots \\ a_{n1}(t) & \dots & a_{nn}(t) \end{bmatrix}, \quad G(t) = \begin{bmatrix} g_1(t) \\ \vdots \\ g_n(t) \end{bmatrix}$$

Otherwise, **nonlinear**.

Def. A linear first order system is **homogeneous** if $G(t) \equiv \vec{0}$.
Otherwise, **nonhomogeneous**.

Thm 4.1 (i) Let $x^{(n)} + a_1(t)x^{(n-1)} + \dots + a_{n-1}(t)\dot{x} + a_n(t)x = g(t)$,
 $x(t_0) = x_0, \dot{x}(t_0) = x_1, \dots, x^{(n-1)}(t_0) = x_{n-1}$ initial conditions,

Then if $\{a_i\}_{i=1,2,\dots,n-1}$, and g are continuous on an open interval I containing t_0 , then \exists a unique solution $x(t)$ on I .

(ii) Let $\dot{X}(t) = A(t)X(t) + G(t), X(t_0) = X_0$ initial cond.

Then if $A(t), G(t)$ are continuous on an open interval I containing t_0 , then \exists unique soln. $X(t)$ on I .

Ex. 4.1 $\frac{d^2x}{dt^2} + \frac{3}{t}\frac{dx}{dt} + \frac{x}{t^2} = 0, x(1) = 0, \dot{x}(1) = 1.$

All coefficients are cont. on $(0, \infty)$, so \exists unique soln.

We can find a general soln $x_{gen}(t) = c_1 t^{-1} + c_2 t^{-1} \ln t$

$$\dot{x}_{gen}(t) = -c_1 t^{-2} + c_2 t^{-2} - c_2 t^{-2} \ln t$$

Solve the IVP $x(1) = 0 = c_1$

$$\dot{x}(1) = 1 = -c_1 + c_2 \Rightarrow c_2 = 1$$

$$\Rightarrow x(t) = t^{-1} \ln t.$$